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COMPETENCE AREAS		STEPS OF COMPETE	ENCE DEVELOPMENT			
1. Maintaining and assuring the reliability of mechatronic systems.	He/She is able to perform the basic scheduled maintenance on mechatronic machines and sys- tems and adhere to the equip- ment maintenance plans.	He/She is able to master the maintenance procedures for mechatronic systems such as the use of service documents and maintenance plans and, if faced with new challenges, is able to make the necessary adaptations.	He/She is able to use preventive maintenance to assure the trou- ble-free operation of mechatronic systems. In addition, he/she is able to mod- ify operational sequences to im- plement quality-assurance measures.	He/She is able to develop the necessary procedures for mainte- nance of mechatronic devices and systems, and is able to schedule the mainte- nance and quality-assurance procedures.		
	Partial competences/ Learning or	utcomes:				
	He/She is able to clean and preserv	ve mechatronic components.				
	He/She is able to grease mechanication	al parts of mechatronic systems (e.g.	slide bearings).			
	He/She is able to check and fill up I	iquid levels in mechatronic machines	(e.g. gear oil, hydraulic oil).			
	He/She is able to replace expendable parts and auxiliary supplies in a mechatronic system (e.g. gaskets, expandable parts of drive components).					
	He/She is able to readjust adjustable	le parts in a mechatronic system (e.g	. chain tension, friction belts).			
	He/She is able to add work results i	in an existing maintenance plans guid	led by a supervisor.			

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	Partial competences/ Learning or	utcomes:				
	He/She is able to perform the scheduled maintenance on a complex mechatronic machine.					
	He/She is able to deploy occupationally related health, safety and accident prevention measures.					
	He/She is able to use energy supply and materials in an environmentally friendly manner.					
	He/She is able to avoid waste and to dispose waste materials in an environmentally friendly manner.					
	He/She is able to add working resul	Its in maintenance plans autonomous	sly.			







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	Partial competences/ Learning or	utcomes:			
	He/She is able to inspect mechatron	nic systems.			
	He/She is able to check function of	safety systems and execute protocol	checks.		
	He/She is able to maintain mechatronic systems in accordance with maintenance plans.				
	He/She is able to exchange parts subject to wear and tear as part of preventative maintenance (e.g. belts, roller bearings).				
	He/She is able to dismantle and assemble devices and subassemblies and label parts with regard to position and functional alignment (e.g. to replace tooth wheels).				
	He/She is able to identify and to rec	ctify defects and errors and to docum	ent them.		

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	Partial competences/ Learning outcomes:				
	He/She is able to select test methods and test equipment.				







2. Installing and dismantling mechatronic systems and facilities	He/She is able to use written instructions to install and dismantle individual components (e.g. sensors, actuators, drives, motors, transport systems, racks) that form a func- tional group of mechatronic systems.	He/She is able to master the selection of hardware and software for mechatronic sys- tems (e.g. sensors, actuators, interfaces, communication procedures) and is able to provide and test simple programmable logic control programs (PLC) according to produc- tion process requirements.	He/She is able to provide independent mechatronic solutions for the construction of production lines, assure their overall ability to function, and, in addition, is able to use both existing and modified standard components.		
	Partial competences/ Learning outcomes:				
	He/She is able to identify the length and necessary connection of pneumatic / hydraulic piping systems based on technical drawings.				
	He/She is able to connect electrical sensors (e.g. capacitive, inductive, piezoelectric force sensor) based on technical drawings.				
	He/She is able to realize the power supply of servo drives, asynchronous and d.c. motors under safety and precaution aspects.				
	He/She is able to assemble and adjust mechan	ical components (e.g. fixing with screws and bolts	; welding).		







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	Partial competences/ Learning outcomes:			
	He/She is able to transfer information of wiring a	and pneumatic / hydraulic schemes into an assem	bly plan containing the correct step sequences.	
	He/She is able to carry out the correct assembling / dismantling by labelling every mechanical device (e. g. replacing drive components).			
	He/She is able to conduct functional testing by considering the given operational parameters.			
	He/She is able to design, run and document a fi	inal acceptance test.		







2. Installing and dismantling mechatronic systems and facilities	He/She is able to use written instructions to install and dismantle individual components (e.g. sensors, actuators, drives, motors, transport systems, racks) that form a functional group of mechatronic systems.	He/She is able to master the selection of hardware and software for mechatronic sys- tems (e.g. sensors, actuators, interfaces, communication procedures) and is able to provide and test simple programmable logic control programs (PLC) according to produc- tion process requirements.	He/She is able to provide independent mechatronic solutions for the construction of production lines, assure their overall ability to function, and, in addition, is able to use both existing and modified standard compo- nents.	
	Partial competences/ Learning outcomes:			
	He/She is able to modify an existing device in a mechatronic system by searching for alternative solutions (e.g. coupling, conveyor belt).			
	He/She is able to test the optimized mechatronic system.			
	He/She is able to detect failure modes and sugge	est possible solutions.		







3. Installing and adjusting mechatronic components in systems and production lines	He/She is able to install and adjust mecha- tronic components (e.g. individual electro pneumatic standardized valves, sensor and actuator units).	He/She is able to install and adjust compo- nents of mechatronic subsystems (e.g. linear drives, measuring systems, transport drives, and transport systems).	He/She is able to install and adjust complex mechatronic facilities that include diverse technologies and instrumentation and control (I&C) equipment, adjust the associated pa- rameters, test the facilities overall functions and assure their reliability.	
	Partial competences/ Learning outcomes:			
	He/She is able to assemble mechatronic compo	onents (e.g. plug-in modules, housings and circuit	unit combinations).	
	He/She is able to wire up and label components for electrical auxiliary and circuit units.			
	He/She is able to adjust single components in an existing mechatronic system.			
	He/She is able to install fluidic components, in particular cylinders and valves.			
	He/She is able to prepare, lay and connect up p	ipes and hoses.		
	He/She is able to check for leaks.			







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	Partial competences/ Learning outcomes:				
	He/She is able to use bearing assembling sets.				
	He/She is able to assemble and adjust drive elements (e.g. drive axes and bearings, couplings, belt- and chain drives, gearboxes, el. motor reducers).				
	He/She is able to use electrical measurement devices and test equipment.				
	He/She is able to use mechanical measurement	t devices and test equipment.			
	He/She is able to test and adjust equipment for	identification of limit values (e.g. switches and se	nsors).		

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3. Installing and adjusting mechatronic components in systems and production lines	He/She is able to install and adjust mechatronic components (e.g. individual electro pneumatic standardized valves, sensor and actuator units).	He/She is able to install and adjust compo- nents of mechatronic subsystems (e.g. linear drives, measuring systems, transport drives, and transport systems).	He/She is able to install and adjust complex mechatronic facilities that include diverse technologies and instrumentation and con- trol (I&C) equipment, adjust the associated parameters, test the facilities overall func- tions and assure their reliability.	
	Partial competences/ Learning outcomes:			
	He/She is able to assemble and adjust mechatro	nic system which has several movement functions		
	He/She is able to install drive- and transportation systems and connect el. motors with frequency invertors.			
	He/She is able to adapt instrumentation and control equipment to the existing facilities.			
	He/She is able to bring in operation mechatronic facilities.			
	He/She is able to monitor and evaluate the opera	ation of mechatronic facilities.		







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4. Designing, adapting, and building mechatronic systems and facilities on the basis of client needs and site plans	He/She is able to use machine tools con- trolled either manual- ly or via a computer program to fabricate (according to produc- tion designs and customer require- ments) the individual components for mechatronic systems. He/She is able to provide simple de- signs and descrip- tions of mechatronic subsystems and is able to use basic CAD applications.	He/She is able to build simple mecha- tronic subsystems by using engineering drawing and is able to install the devices according to specific production needs. He/She is able to act on extensive knowledge of stand- ards and regulations (e.g. on surface treatments) and is able to use CAD's more advanced func- tions (e.g. interference check).	He/She is able to build mechatronic systems by using both, original con- struction techniques and previously signed parts. He/She is able to fully understand s CAD functions and is able to document system developments (e.g. parts lists, descrip- tions of function, operating instruc- tions).	He/She is able to design and build autonomous mecha- tronic subsystems and, with suitable measuring and test- ing facilities, is able to assess the neces- sary production accu- racy. He/She is able to document the results with quality-control systems.	He/She is able to make independent adaptations to the various devices (in- cluding selection of drives, sensors, PLC) and is able to use CNC programs for building the system. He/She is able to assemble, through a digital mock up, and simulate the function- ing system and use computer aided com- putations (e.g. FEM). He/She is able to perform cost-benefit analyses (e.g. as a basis for deciding whether components should be bought or individually con- structed.)	He/She is able to develop independent- ly complex mecha- tronic systems and is able to calculate the economic usefulness of the system. He/She is able to optimise CNC pro- grams for the manu- facturing of complex mechatronic devices and systems and monitor the automat- ed quantity of an open loop control system.
	Partial competences/	Learning outcomes: no	ot covered by consortiu	IM		

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5. Putting mechatronic systems into operation and providing clients with technical and economic sup- port	He/She is able to put, according to specifications and blueprints, mecha- tronic devices into opera- tion and provide support to the client in the hand- over phase.	He/She is able to put, after considering the enter- prise's needs and basic conditions, the mechatron- ic systems into operation, create the necessary documentation, advise the customer on safe opera- tions of the devices, and advise on future technolo- gy selection.	He/She is able to master, after considering all basic conditions, the start-up of interconnected mecha- tronic systems and ma- chines, and is able to provide the necessary documentation including a manual. He/She is able to review client needs and configure machines that provide solutions. He/She is able to train the customer where necessary and provide support for safety operat- ing procedures.	He/She is able to evaluate customer requirements for mechatronic facilities, develop solutions, and is able to plan the system's implementation and op- eration.	He/She is able to direct, including scheduling and time management, the start-up of the project from the creation of a proposal to the client's acceptance.
	Partial competences/ Learning outcomes: not covered by consortium				







6. Supervising and evaluating both the process sequences of mechatronic systems and facilities and the operational sequence (including quality assurance)	He/She is able to super- vise process sequences according to specifications as well as implement any requested quality control measures.	He/She is able to super- vise independently the process sequences, eval- uate the results, operate an accompanying statisti- cal process control (SPC) for the quality control plan, and prepare simple work schedules, including pro- duction schedule and time management.	He/She is able to operate and supervise mechatron- ic facilities, choose testing and monitoring plans, set up the accompanying SPC, seek the optimal results of the production line according to material flow, and provide work schedules including standard production times.	He/She is able to master the monitoring of complex mechatronic systems using virtual instruments and PPS systems as well as open loop control for the optimi- sation of machinery ar- rangement, material flow analysis, and scheduling.	He/She is able to optimise the process cycles of mechatronic production lines, provide instructions on modifying the PPS systems (e.g. adjustment to SAP systems) and introduce quality systems for continuous improve- ment processes (CIP/KVP).
	Partial competences/ Learning outcomes: not covered by consortium				







7. Installing, configuring, programming and testing hardware and software com- ponents for control and regu- lation of mechatronic sys- tems and facilities	He/She is able to install and con- figure programs for hardware and software components as well as set up simple programmable logic control programs (PLC).	He/She is able to master the selection of hardware and soft- ware for mechatronic systems (e.g. sensors, actuators, interfac- es, communication procedures) and is able to provide and test simple programmable logic con- trol programs (PLC) according to production process requirements.	He/She is able to integrate and configure program-, control- and regulation mechanisms in mecha- tronic systems, program simple devices (in co-operation with developers), and simulate the program sequence before start- up.	He/She is able to develop, test, and configure hardware and soft- ware solutions for networked mechatronic systems, and is able to monitor system conditions with suitable measuring and visualisa- tion tools.	
Partial competences/ Learning outcomes:					
	He/She is able to identify the most important hardware-modules of a PLC. He/She is able to carry out the hardware configuration of a PLC with an established PLC-Software. He/She is able to transfer PLC programs to automation units.				
He/She is able to enter and amend control programs for a module of a mechatronic device (e.g. pick-and-place units).					







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	Partial competences/ Learning outcomes:					
	He/She is able to use technical drawings and specifications in order to select software and hardware components (e.g. proximity switches, pneumatic valves, cylinders).					
	He/She is able to assemble hardware components into modules of mechatronic devices. He/She is able to install sensors and actuators. He/She is able to check the correct function of sensors and actuators for an existing control system.					
	He/She is able to implement a linear program for a mechatronic system (e.g. with timer functions, counters).					
	He/She is able to test the application	on programs in process.				

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	Partial competences/ Learning outcomes:					
	He/She is able to design PLC-programs for a mechatronic system with different modes of operation (e.g. single step, automatic mode). He/She is able to process analogue and digital signals (e.g. with temperature sensors or encoders). He/She is able to implement PLC-programs in order to control the speed of electrical drives (e.g. frequency inverter, servo drive).					
	He/She is able to simulate robot moves in virtual environment via control circuits.					
	He/She is able to map real robot setting to virtual robot setting.					

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7. Installing, configuring, programming and testing hardware and software com- ponents for control and regu- lation of mechatronic sys- tems and facilities	He/She is able to install and configure programs for hardware and software components as well as set up simple program- mable logic control programs (PLC).	He/She is able to master the selection of hardware and soft- ware for mechatronic systems (e.g. sensors, actuators, inter- faces, communication proce- dures) and is able to provide and test simple programmable logic control programs (PLC) according to production process requirements.	He/She is able to integrate and configure program-, control- and regulation mechanisms in mecha- tronic systems, program simple devices (in co-operation with devel- opers), and simulate the program sequence before start-up.	He/She is able to develop, test, and configure hardware and software solutions for networked mechatronic systems, and is able to monitor system conditions with suitable measuring and visualisa- tion tools.	
Partial competences/ Learning outcomes:					
	He/She is able to connect PLCs in an automated system for data exchange (e.g. by using a bus-system). He/She is able to assemble networking components into a control system. He/She is able to control networked peripheral devices (e.g. servo motor drives, frequency inverters). He/She is able to adjust measuring tools.				







8. Preparing and distributing the technical information for adjustment of each enter- prise's mechatronic systems	He/She is able to provide description designs of mechatronic subsystems familiar with the basic CAD applicat	ons and s and is tions.	He/She is able to fully a agement of technical in for mechatronic system pare and adapt these d an enterprise's specific ments.	understand the man- formation documents is and is able to pre- locuments according to operating require-	He/She is al sequence stand the of nance and He/She is parameter functions a and docum tions of the	able to analyse complex operation- ces separately in order to under- connections and draw up mainte- production procedures. able to understand that the system s are important for the equipments' and is able to independently assess nent the wear and general condi- e mechatronic equipment.
	Partial competences/ Learning of	utcomes: no	ot covered by consortiu	Im		
9. Diagnosing and repairing malfunctions with mechatronic systems and facilities, advising clients on avoiding malfunctions, and modifying and expanding mechatronic systems	He/She is able to diagnose and repair errors and malfunctions on the simple components and de- vices in the mechatronic systems. He/She is able to use the neces- sary checking, measuring and diagnostic tools.	He/She is a pendently tronic prod the help of diagnostic expert syst error docu	able to correct inde- problems in mecha- uction equipment with (computer-aided) systems and the use of tems, databases and mentations.	He/She is able to diagr repair errors and distur complex mechatronic e and is able to advise cl how to avoid sources o tions through changes grades in the equipmen system.	nose and bances in equipment ients on f malfunc- or up- nt and	He/She is able to develop, through analyses of malfunctions in the mechatronic equipment, a monitoring and diagnostic system.
	Partial competences/ Learning of	utcomes: no	ot covered by consortiu	im		

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